

CONTENTS

1	MODELING OF KINEMATIC RELATIONS IN MOBILE TECHNICS	11
1.1	MODELING OF KINEMATIC RELATIONS OF WHEELED VEHICLES	11
1.1.1	<i>Equations of oscillatory motion</i>	15
1.1.2	<i>Suspension systems of wheeled vehicles</i>	15
1.1.3	<i>Simulation of suspension</i>	17
1.1.4	<i>Mathematical model of the vehicle</i>	20
1.1.5	<i>Experimental measurements</i>	22
1.1.6	<i>Experimental results</i>	23
1.1.7	<i>Parameter optimization</i>	27
1.1.8	<i>Development trends in mobile technics wheel chassis construction</i>	31
1.2	MODELING OF KINEMATIC RELATIONS OF TRACKED VEHICLES	38
1.2.1	<i>Springing systems of tracked vehicles</i>	38
1.2.2	<i>Modeling springing simulation of tracked vehicle</i>	46
1.2.3	<i>Modernization of the system of track vehicle springing</i>	50
2	MODELING OF STRENGTH RELATIONS OF SELECTED ELEMENTS IN MOBILE TECHNICS	57
2.1	FINITE ELEMENT ANALYSIS IN MECHANICAL ENGINEERING	57
2.1.1	<i>Dynamic equilibrium equations</i>	58
2.1.2	<i>Kinematic equations</i>	60
2.1.3	<i>Constitutive equations</i>	62
2.1.4	<i>Tetrahedron element</i>	63
2.1.5	<i>Hexahedron element</i>	67
2.1.6	<i>Minimum energy principle</i>	71
2.2	STRENGTH ANALYSES	73
2.2.1	<i>Strength analysis of road wheel arm with torsion rod</i>	73
2.2.2	<i>Strength analysis of track link connector</i>	80
2.2.3	<i>Armor protection of military mobile technics</i>	86
2.2.4	<i>Strength analysis of armor protection</i>	93
3	APPENDIX	105